



8-bit Serial-In/Parallel-Out Constant Current Driver

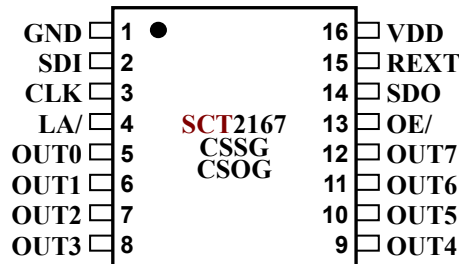
Product Description

The SCT2167 serial-interfaced LED driver sinks 8 LED clusters with constant current to keep the uniform intensity of LED displays. In applications, an external resistor is used to set the full-scale constant output current from 5mA up to 45mA. The SCT2167 guarantees each output can endure maximum 17V DC voltage stress. The built-in shift registers and data latches making the SCT2167 effective solution in driving LED display. The output enable function gates all 8 outputs on and off, and is fast enough to be used as PWM input for LED intensity control. Since the serial data input rate can be reached up to 25MHz, the SCT2167 will satisfy system which needs high volume data transmission to control the LED

Features

- ◆ 8 constant current sinkers with output voltage sustainable to 17V
- ◆ Constant output current : 5 – 30/45mA@3.3/5V
- ◆ Excellent regulation to load, supply voltage and temperature
 - Temperature regulation: $\pm 0.005\%/^{\circ}\text{C}$
 - load regulation: $\pm 0.1\%/V$
 - line regulation: $\pm 0.5\%/V$
- ◆ High current matching accuracy: $\pm 1\%$ between outputs, $\pm 2\%$ between ICs
- ◆ Fine grayscale response with 180ns PWM pulse width
- ◆ Dropout voltage 0.5V@20mA, $V_{DD}=5V$
- ◆ CMOS Schmitt trigger inputs with clock rate up to 25MHz @ cascade connection
- ◆ The constant current value of 8 outputs is set by a single external resistor
- ◆ Interlaced 30ns delay of output, preventing instant current surge and output bouncing overstress
- ◆ Built-in power on reset(POR) circuit forces all the outputs off while power on
- ◆ Package: SSOP16 and SOP16
- ◆ Applications: LED Displays, Variable Message Signs, Illumination, LED Traffic Signs

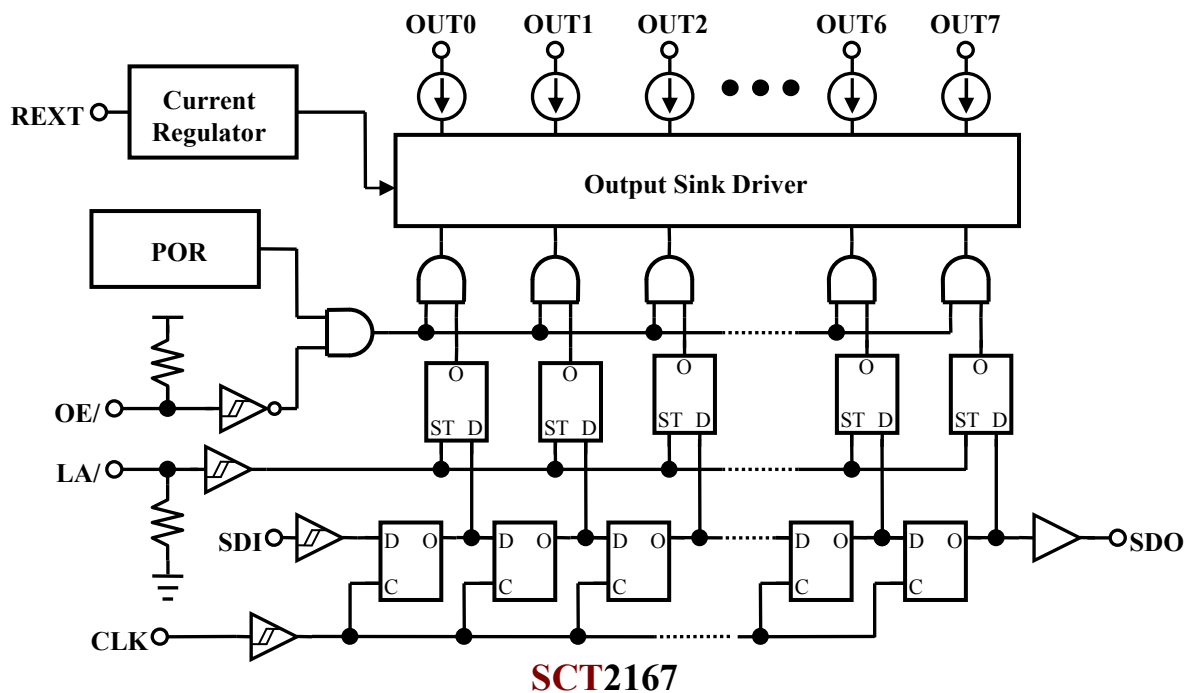
Pin Configurations



Terminal Description

Pin Name	Pin No.	I/O	Function
GND	1	-	Ground terminal
SDI	2	I	Serial input terminal of data shift register
CLK	3	I	Clock input terminal of shift register, data is sampled at the rising edge of CLK.
LA/	4	I	Data is latched when LA/ is low. Data on shift register goes through when LA/ is high.
OUT[0:7]	5-12	O	Open-drain, constant-current outputs.
OE/	13	I	Input terminal of output enable signal. Output is enabled when OE/ is low.
SDO	14	O	Output terminal of serial-data output to the SDI of next SCT2167.
REXT	15	I/O	Synchronous signal, daisy chain output terminal.
VDD	16	-	Supply voltage terminal

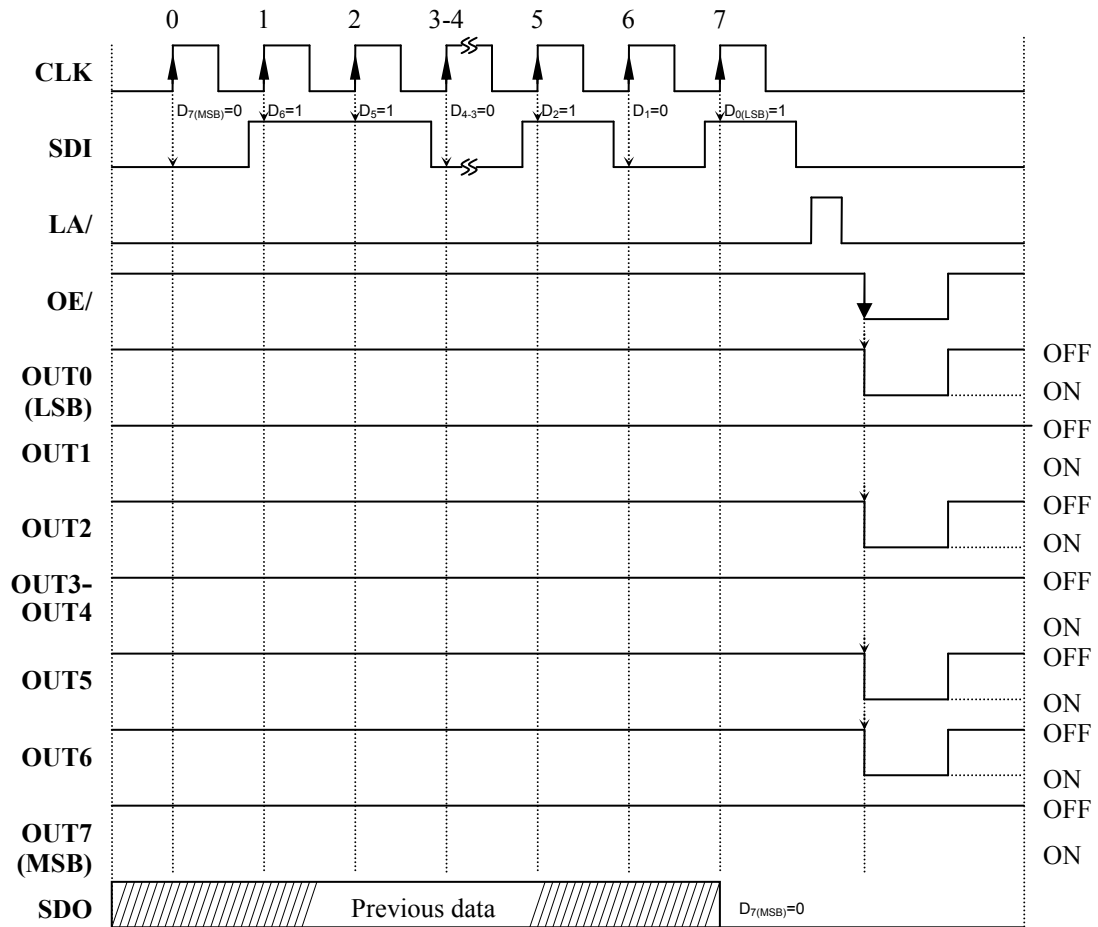
Block Diagram

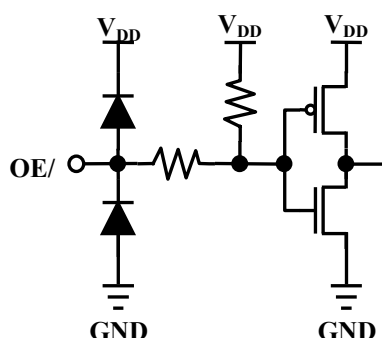
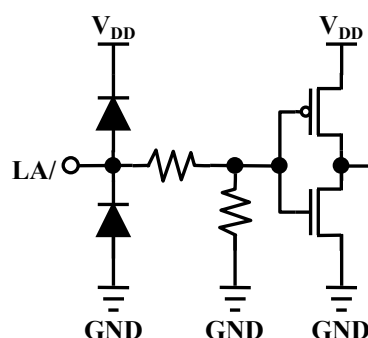
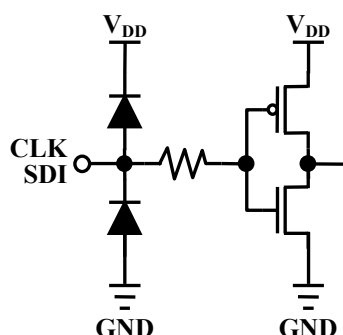
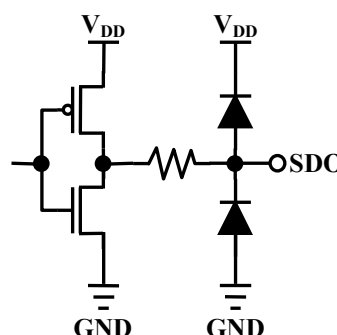


Truth Table

CLK	LA/	OE/	SDI	OUT0 ~ OUT7	SDO
	H	L	D_n	D_n D_{n-1} ---- D_{n-6} D_{n-7}	D_{n-7}
	L	L	D_{n+1}	No change	D_{n-6}
	H	L	D_{n+2}	D_{n+2} D_{n+1} ---- D_{n-4} D_{n-5}	D_{n-5}
	X	L	D_{n+3}	D_{n+2} D_{n+1} ---- D_{n-4} D_{n-5}	D_{n-5}
	X	H	D_{n+3}	Off	D_{n-5}

Timing Diagram



Equivalent Circuits of Inputs (1)**Equivalent Circuits of Input (2)****Equivalent Circuits of Inputs (3)****Equivalent Circuits of Output****Selector Guide**

Part	Number of Outputs	Max Output Current (mA)	Min PWM Pulse Width (ns)	Supply Voltage (V)	Error Detection
SCT2110	8	180	100	5	NA
SCT2168	8	120	120	3.3/5	NA
SCT2169	8	120	120	3.3/5	Yes
SCT2167	8	60	180	3.3/5	NA
SCT2210	16	120	50	5	NA
SCT2026	16	90	120	3.3/5	NA
SCT2027	16	90	120	3.3/5	Yes
SCT2024	16	60	180	3.3/5	NA

Ordering Information

Part	Marking	Package	Unit per reel(pcs)
SCT2167CSSG	SCT2167CSSG	Green SSOP16	2500
SCT2167CSOG	SCT2167CSOG	Green SOP16	2500

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Maximum Ratings ($T_A = 25^\circ\text{C}$)

Characteristic	Symbol	Rating	Unit
Supply voltage	V_{DD}	7.0	V
Input voltage	V_{IN}	$-0.2 \sim V_{DD}+0.2$	V
Output current	I_{OUT}	60	mA/Channel
Output voltage	Outputs	$-0.2 \sim V_{DD}+0.2$	V
	OUT0~OUT7	$-0.2 \sim 17$	V
Total GND terminals current	I_{GND}	480	mA
Power dissipation	SSOP16	1.07	W
	SOP16	1.47	
Thermal resistance	SSOP16	117	$^\circ\text{C/W}$
	SOP16	85	
Operating junction temperature	$T_{J(max)}$	150	$^\circ\text{C}$
Operating temperature	T_{OPR}	$-40 \sim +85$	$^\circ\text{C}$
Storage temperature	T_{STG}	$-55 \sim +150$	$^\circ\text{C}$

The absolute maximum ratings are a set of ratings not to be exceeded. Stresses beyond those listed under "Maximum Ratings" may cause the device breakdown, deterioration even permanent damage. Exposure to the maximum rating conditions for extended periods may affect device reliability.

Recommended Operating Conditions ($T_A = -40$ to 85°C unless otherwise noted)

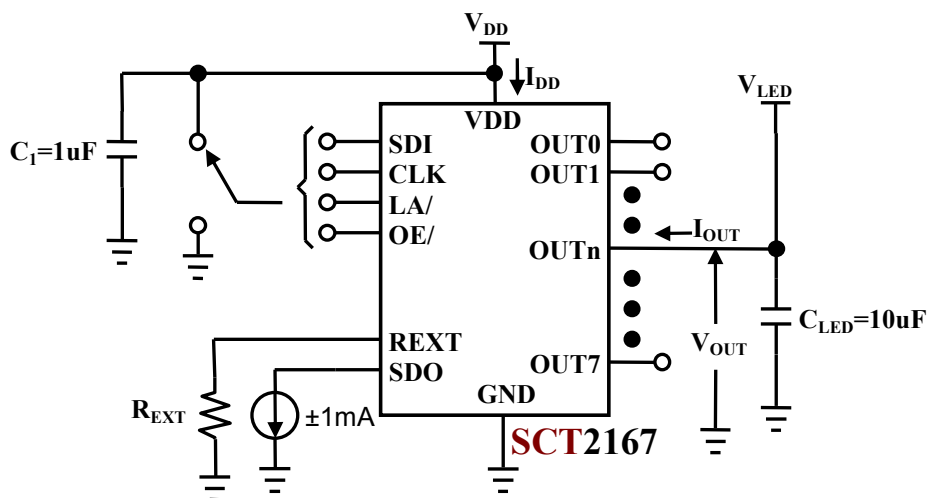
Characteristic	Symbol	Conditions	Min.	Typ.	Max.	Unit
Supply voltage	V_{DD}	-	3	-	5.5	V
Output voltage	V_{OUT}	Output OFF	-	-	17	V
		Output ON	-	1 ¹	4 ²	V
Output current	I_{OUT}	$V_{DD}=3.3/5\text{V}, V_{OUT}=1\text{V}$	5	-	30/45	mA
Input voltage	V_{IH}	input signals	$0.7V_{DD}$	-	V_{DD}	V
	V_{IL}		0	-	$0.3V_{DD}$	V
OE/ pulse width	$t_{W(OE)}$	$V_{DD}=3.3\text{V}/5\text{V}$	180	-	-	ns

- The output current keep constant in range of 5-45mA if $V_{OUT}=1\text{V}$.
However, user can minimize V_{OUT} to reduce power dissipation according to used current, e.g., set V_{OUT} to 0.6V if $I_{OUT}=20\text{mA}$.
- The maximum V_{out} is package thermal limited, user should keep V_{out} under maximum power dissipation.

Electrical Characteristics ($V_{DD}=3.3/5V$, $T_A=25^\circ C$ unless otherwise noted)

Characteristic	Symbol	Conditions	Min.	Typ.	Max.	Unit	
Digital inputs voltage	V_{IH}	-	$0.7V_{DD}$	-	V_{DD}	V	
	V_{IL}	-	0	-	$0.3V_{DD}$	V	
SDO output voltage	V_{OH}	$V_{DD}=3.3/5V$, $I_{OH}=-1mA$	$V_{DD}-0.4$	-	-	V	
	V_{OL}	$V_{DD}=3.3/5V$, $I_{OL}=+1mA$	-	-	0.4	V	
Output leakage current	I_{OL}	$V_{OUT}=17V$	-	-	0.5	μA	
Output current	I_{OUT}	$V_{OUT}=1V$, $R_{EXT}=900\Omega$	-	21	-	mA	
Current bit skew ¹	dl_{OUT1}	$V_{OUT}=1V$, $R_{EXT}=900\Omega$	-	± 1	± 2	%	
Chip skew ²	dl_{OUT2}	$V_{OUT}=1V$, $R_{EXT}=900\Omega$	-	± 2	± 5	%	
Line regulation ³ I_{OUT} vs. V_{DD}	$\%/dV_{DD}$	$3V < V_{DD} < 5.5V$, $V_{OUT} > 1V$, $R_{EXT}=900\Omega$	-	± 0.5	± 1	%/V	
Load regulation ⁴ I_{OUT} vs. V_{OUT}	$\%/dV_{OUT}$	$1V < V_{OUT} < 4V$, $I_{OUT}=42mA$, $R_{EXT}=900\Omega$	-	± 0.1	± 0.5	%/V	
Temp. regulation ⁵ I_{OUT} vs. T_A	$\%/dT_A$	$-20^\circ C < T_A < 80^\circ C$, $I_{OUT}=10mA\sim 90mA$, $V_{DD}=5V$	-	± 0.005	-	%/°C	
Pull-up resistor	R_{UP}	OE/	-	420	-	K Ω	
Pull-down resistor	R_{DOWN}	LA/	-	400	-	K Ω	
Supply current	OFF	$I_{DD(OFF)1}$	$V_{DD}=3.3/5V$, $R_{EXT}=\text{Open}$, $OUT[0:7]=\text{OFF}$	-	2	3	mA
		$I_{DD(OFF)2}$	$V_{DD}=3.3/5V$, $R_{EXT}=900\Omega$, $OUT[0:7]=\text{OFF}$	-	5	7	
	ON	$I_{DD(ON)}$	$V_{DD}=3.3/5V$, $R_{EXT}=900\Omega$, $OUT[0:7]=\text{ON}$	-	7/8	10	

1. Bit skew= $(I_{OUT}-I_{AVG}) / I_{AVG}$, where $I_{AVG}=(I_{OUT(max)}+I_{OUT(min)})/2$
2. Chip skew= $(I_{AVG}-I_{CEN}) / I_{CEN} * 100(\%)$, where I_{CEN} is the statistics distribution center of output currents.
3. Line regulation= $[I_{OUT}(V_{DD}=5.5V)-I_{OUT}(V_{DD}=3V)] / \{ [I_{OUT}(V_{DD}=5.5V)+I_{OUT}(V_{DD}=3V)]/2 \} / (5.5V-3V) * 100(\%/V)$
4. Load regulation= $[I_{OUT}(V_{OUT}=4V)-I_{OUT}(V_{OUT}=1V)] / \{ [I_{OUT}(V_{OUT}=4V)+I_{OUT}(V_{OUT}=1V)]/2 \} / (4V-1V) * 100(\%/V)$
5. Temperature regulation= $[I_{OUT}(T_A=80^\circ C)-I_{OUT}(T_A=-20^\circ C)] / \{ [I_{OUT}(T_A=80^\circ C)+I_{OUT}(T_A=-20^\circ C)]/2 \} / (80^\circ C+20^\circ C) * 100(\%/^\circ C)$

Test Circuit for Electrical Characteristics

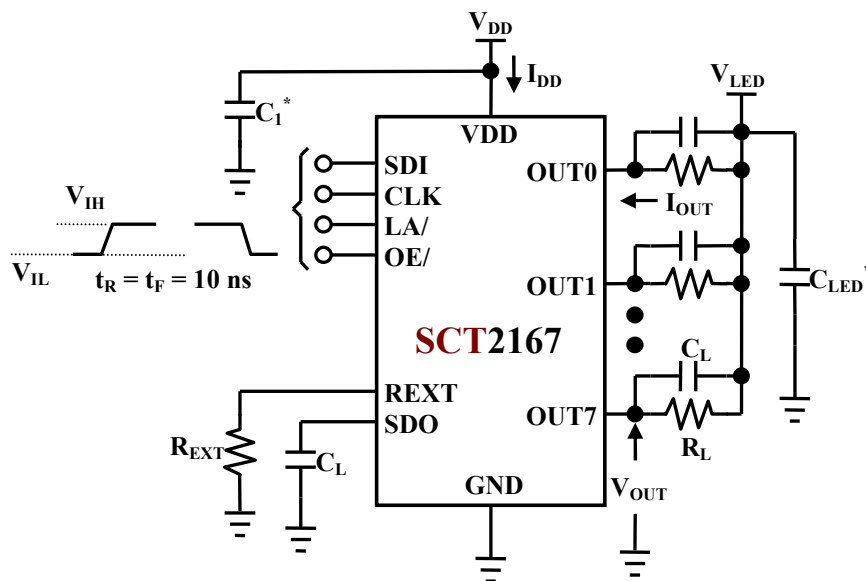
*Place C_1/C_{LED} as close to IC VDD/OUT pin(not supply source) as possible.

Switching Characteristics ($T_A=25^\circ\text{C}$ unless otherwise noted)

Characteristic		Symbol	Conditions	Min.	Typ.	Max.	Unit
Propagation delay time ("L" to "H")	CLK - OUTn	t_{PLH1}	$V_{DD} = 3.3/5\text{V}$ $V_{LED} = 5\text{V}$ $V_{IH} = V_{DD}$ $V_{IL} = \text{GND}$ $R_{EXT} = 900\Omega$ $R_L = 180\Omega$ $C_L = 10\text{pF}$ $C_1 = 1\mu\text{F}$ $C_{LED} = 10\mu\text{F}$	-	80	100	ns
	LA/ - OUTn	t_{PLH2}		-	80	100	ns
	OE/ - OUT0	t_{PLH3}		-	80	100	ns
	CLK - SDO	t_{PLH}		-	20	40	ns
Propagation delay time ("H" to "L")	CLK - OUTn	t_{PHL1}		-	80	100	ns
	LA/ - OUTn	t_{PHL2}		-	80	100	ns
	OE/ - OUT0	t_{PHL3}		-	80	100	ns
	CLK - SDO	t_{PHL}		-	20	40	ns
Pulse width	CLK	$t_{W(\text{CLK})}$		-	-	-	ns
	LA/	$t_{W(L)}$		-	-	-	ns
	OE/	$t_{W(\text{OE})}$		-	-	-	ns
Setup time for SDI		$t_{S(D)}$		-	-	-	ns
Hold time for SDI		t_{HD}		-	-	-	ns
Setup time for LA/		$t_{S(L)}$		-	-	-	ns
Hold time for LA/		$t_{H(L)}$		-	-	-	ns
SDO rise time		t_{SDOR}		-	20	-	ns
SDO fall time		t_{SDOF}	-	20	-	ns	
Output rise time of I_{OUT}		t_{OR}	-	80	100	ns	
Output fall time of I_{OUT}		t_{OF}	-	80	100	ns	
Delayed output		t_{DR}	OUT _{EVEN} to OUT _{ODD}	-	30	-	ns
		t_{DF}		-	30	-	ns
Slow CLK rise time ¹		t_R	Cascade	-	-	500	ns
Slow CLK fall time		t_F		-	-	500	ns

1. It may not be possible to achieve the timing required for data transfer between two cascaded drivers if t_R/t_F is large.

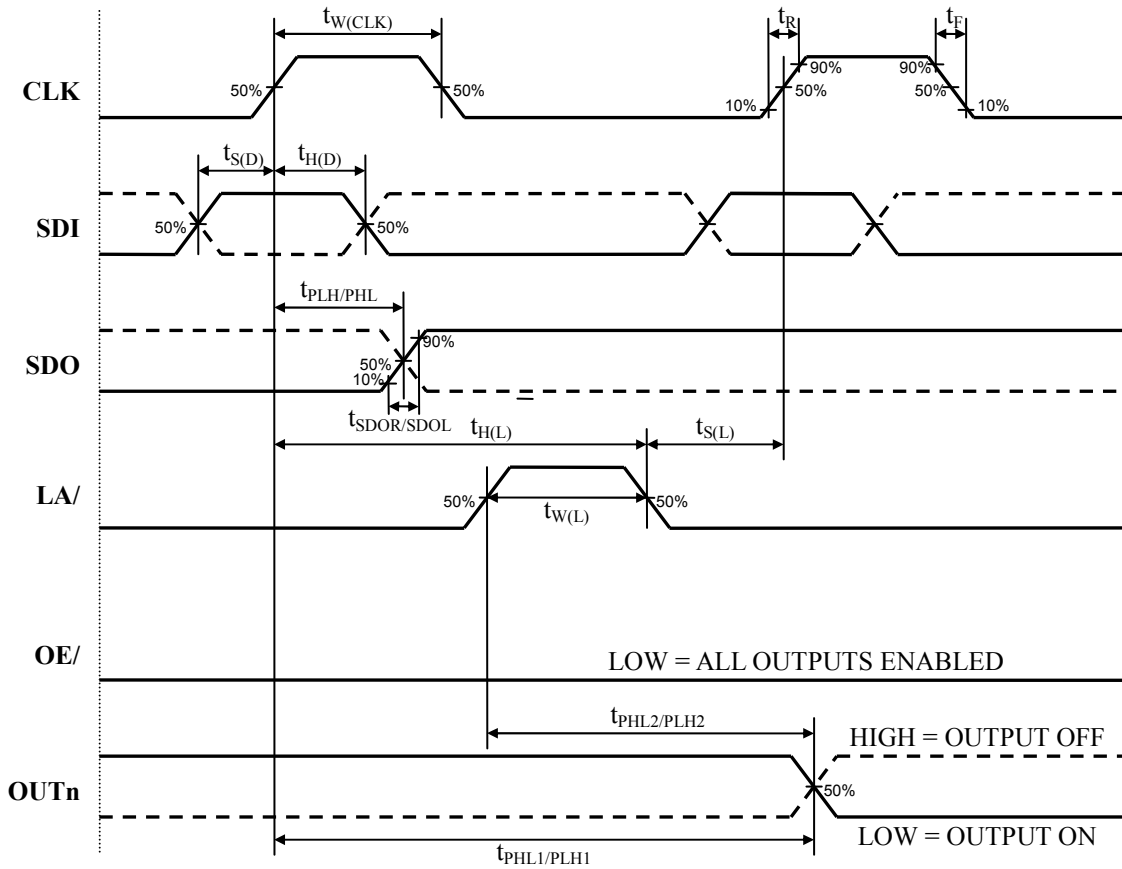
Test Circuit for Switching Characteristics



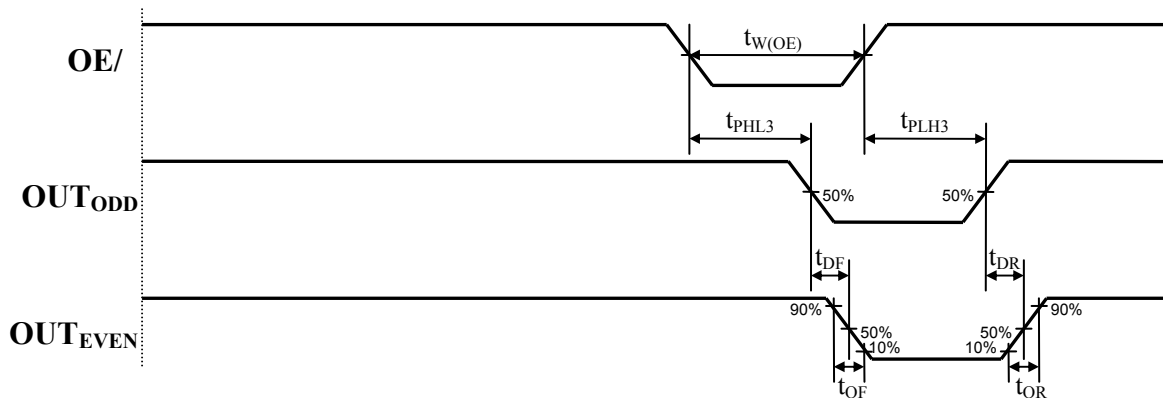
*Place C_1/C_{LED} as close to IC VDD/OUT pin(not supply source) as possible.

Timing Waveform

LA/ Control Output

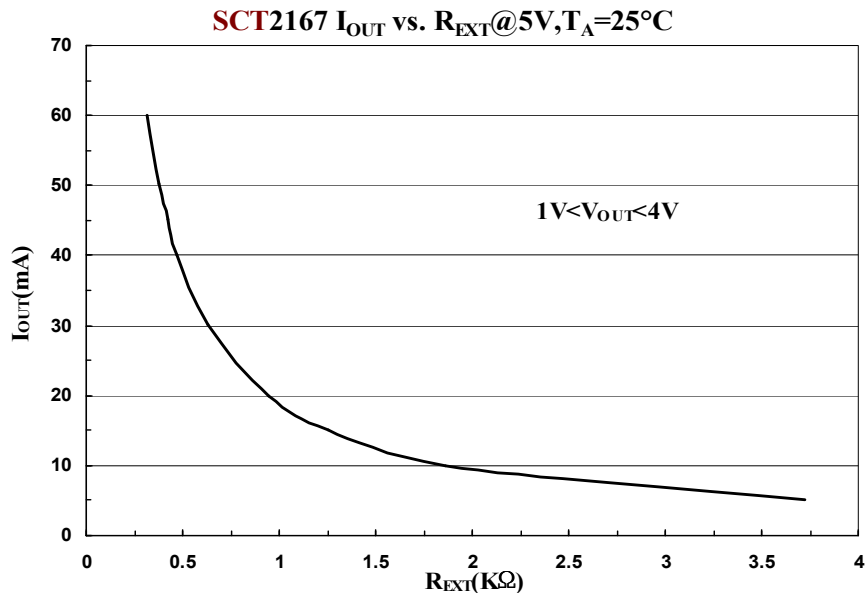


OE/ Control Output



Adjusting Output Current

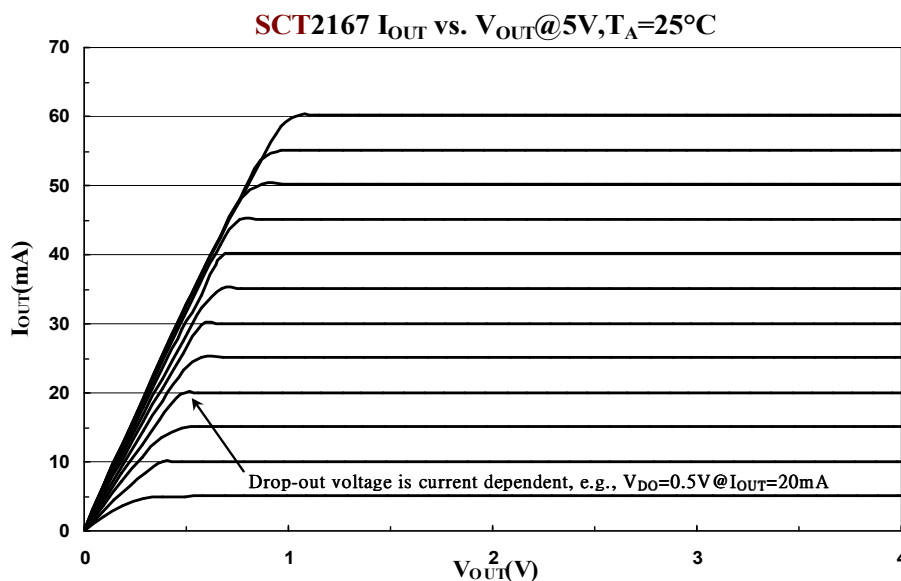
The SCT2167's output current (I_{OUT}) are set by one external resistor at pin REXT. The output current I_{OUT} versus resistance of R_{EXT} is shown as the following figure.

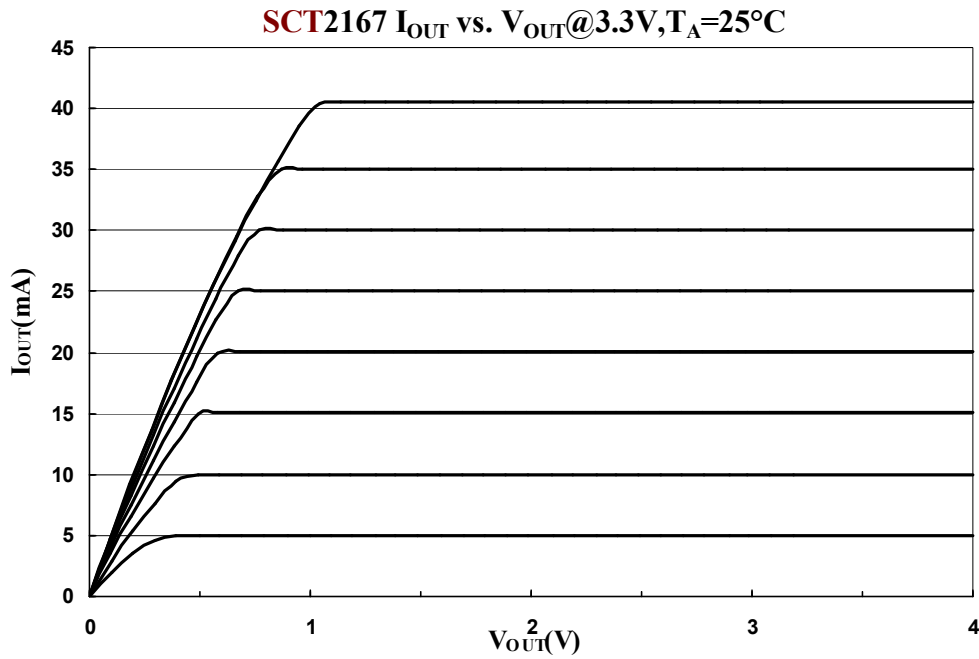


According to SCT2167' I-V curve, the output voltage should be larger than 1V to get 45 mA constant current. By applying proper output voltage, the SCT2167' output current set by an external resistor is approximate to: $I_{OUT} = 30(630 / R_{EXT})$ (mA) (chip skew < $\pm 5\%$). Thus the output current is set to be about 21mA at $R_{EXT} = 900\Omega$.

Output Characteristics

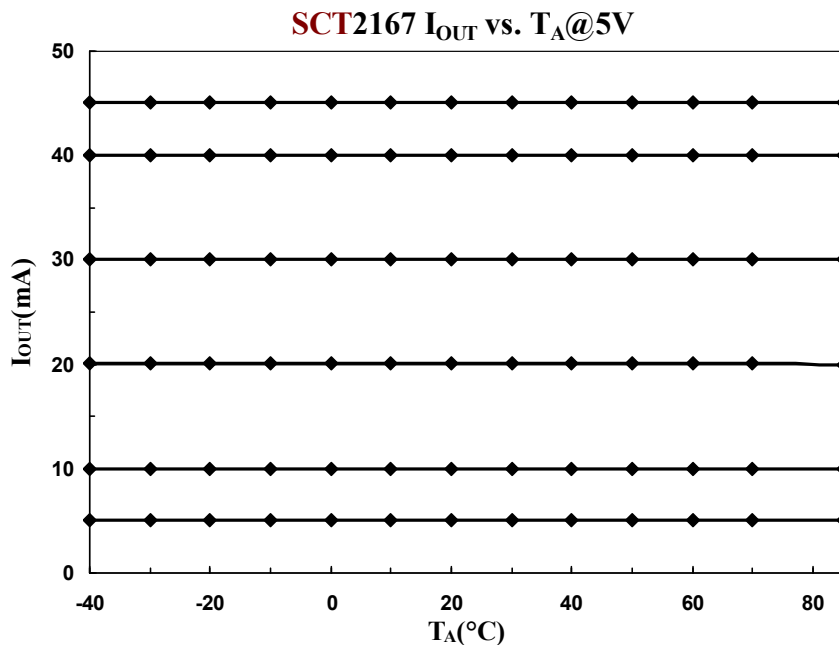
The current characteristic of output curve is flat. The output current can be kept constant regardless of the variations of LED forward voltage when $V_{OUT} > V_{DO}$ (Drop-Out voltage). The relationship between I_{OUT} and V_{OUT} is shown below. The output voltage should be kept as low as possible to prevent the SCT2167 from being overheated.





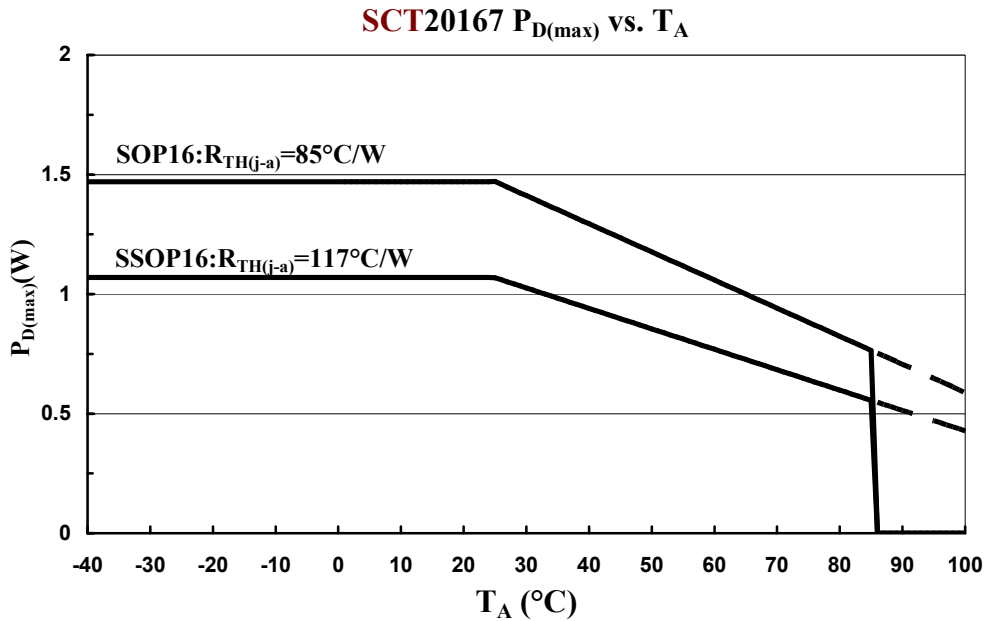
Excellent Temperature Regulation

The constant current driver requires not only the characteristics of supply and load voltage independence, but also temperature invariance. A well thermal stable reference circuit is designed within the SCT2167. Users can get the stable output current over recommended current range $I_{OUT}=5\text{mA}\sim 45\text{mA}$ with ambient temperature (T_A) widely varying from -40°C to 85°C .



Power Dissipation

The maximum power dissipation ($P_{D(max)}$) of a semiconductor chip varies with different packages and ambient temperature. It's determined as $P_{D(max)} = (T_{J(max)} - T_A) / R_{TH(j-a)}$ where $T_{J(max)}$: maximum chip junction temperature is usually considered as 150°C, T_A : ambient temperature, $R_{TH(j-a)}$: thermal resistance. Since $P=IV$, for sinking larger I_{OUT} , users had better add proper voltage reducers on outputs to reduce the heat generated from the SCT2167.

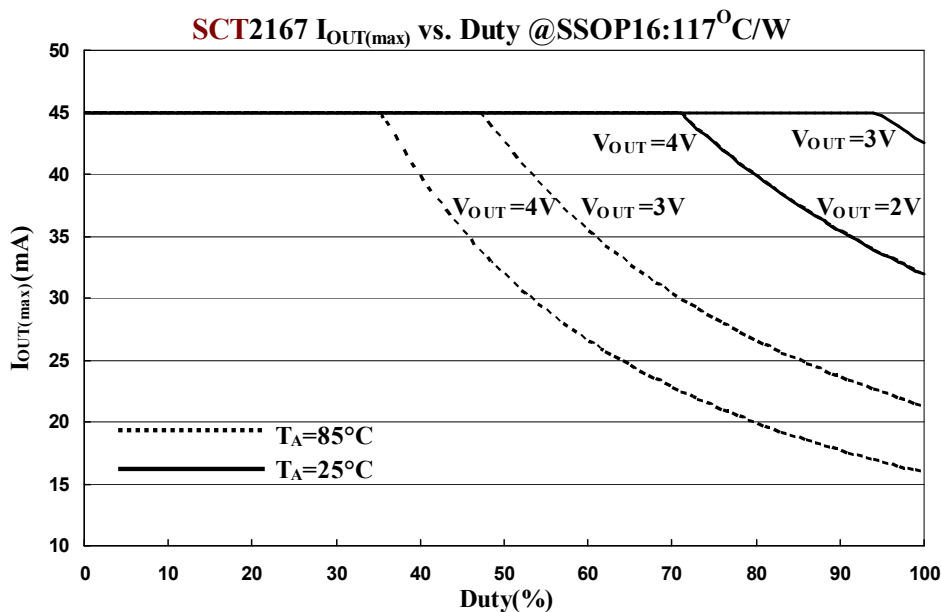


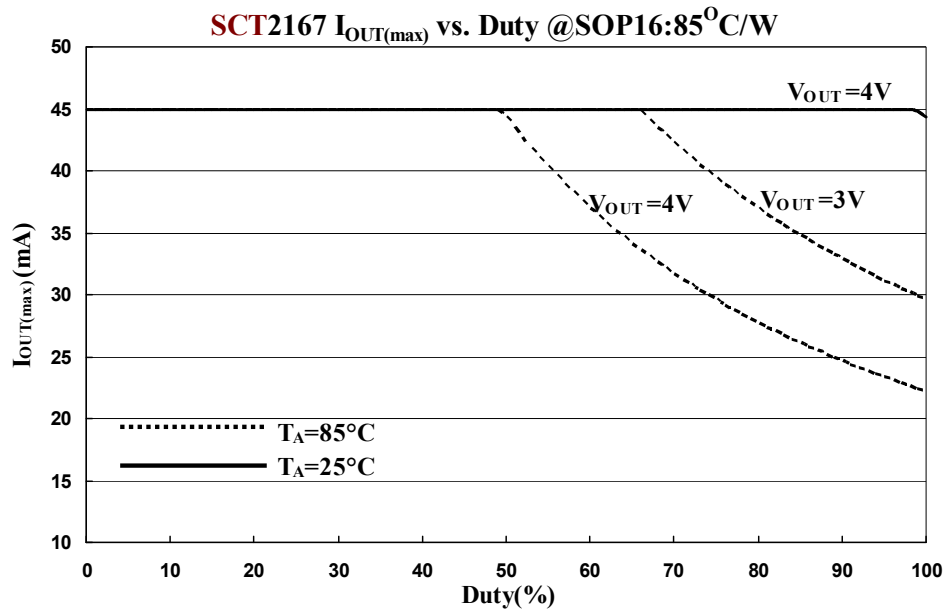
Limitation on Maximum Output Current

The maximum output current vs. duty cycle is estimated by:

$$I_{OUT(max)} = (((T_{J(max)} - T_A) / R_{TH(j-a)}) - (V_{DD} * I_{DD})) / V_{OUT} / \text{Duty} / N$$

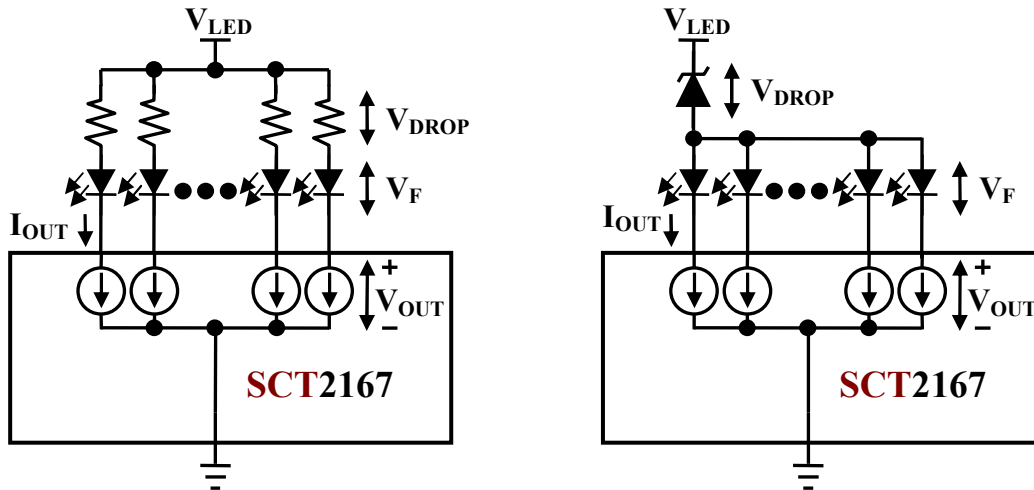
where $T_{J(max)} = 150^\circ\text{C}$, $N = 8$ (all ON)



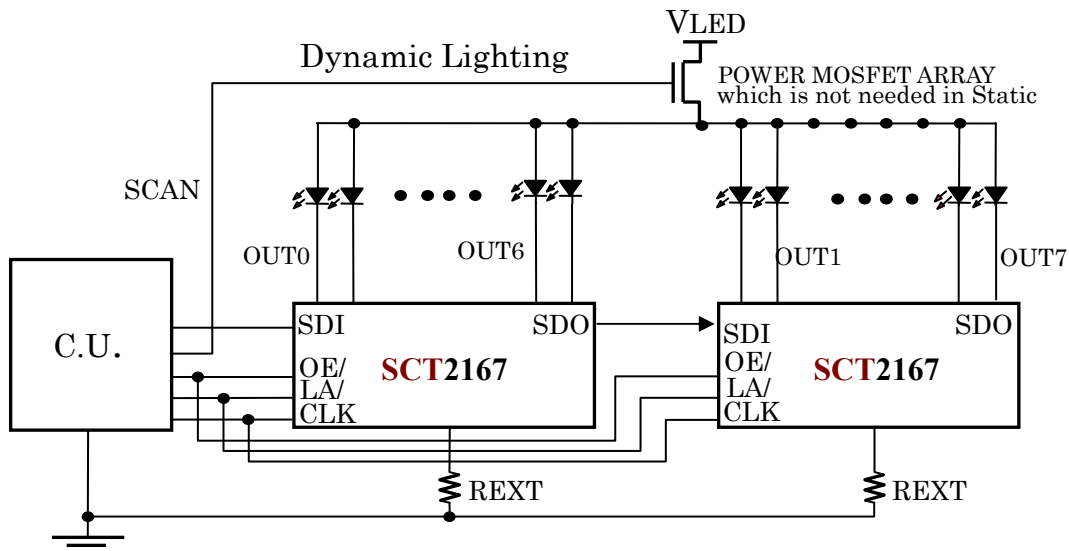


Load Supply Voltage (V_{LED})

The SCT2167 can be operated very well when V_{OUT} ranges from 1V to 4V. However, it is recommended to use the lowest possible supply voltage or set a voltage reducer to reduce the V_{OUT} voltage, at the same time reduce the power dissipation of the SCT2167. Suggested V_{OUT} is to be set greater than V_{DO} and less than 1V. The V_{DO} is dependent on the I_{OUT} current as indicated in section "Output Characteristics". Follow the diagram instructions shown below to lower down the output voltage. This can be done by adding additional resistor or zener diode, thus $V_{OUT} = V_{LED} - V_{DROP} - V_F$.



Typical Application

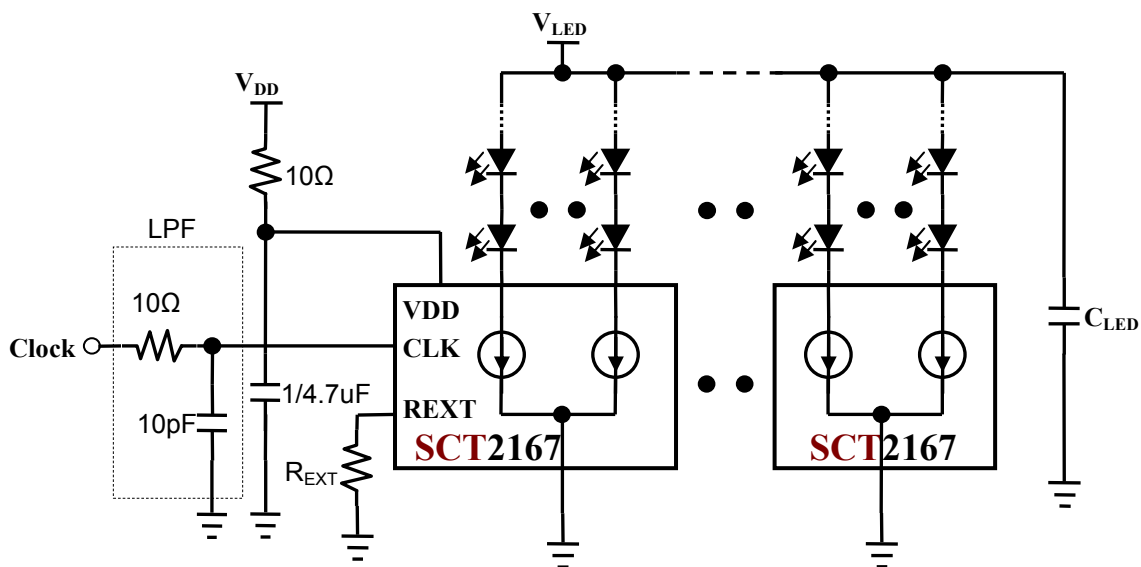


PCB Design Considerations

Use the following general guide-line when designing printed circuit boards (PCB):

Decoupling Capacitor

Place a decoupling capacitor e.g. 1uF between VDD and GND pins of SCT2167. Locate the capacitor as close to the SCT2167 as possible. This is normally adequate for static LED driving. For dynamic scan or PWM applications, it is suggested to add an additional capacitor of 4.7uF or more to each supply for every SCT2167. The necessary capacitance depends on the LED load current, PWM switching frequency, and serial-in data speed. Inadequate VDD decoupling can cause timing problems, and very noisy LED supplies can affect LED current regulation.



External Resistor (R_{EXT})

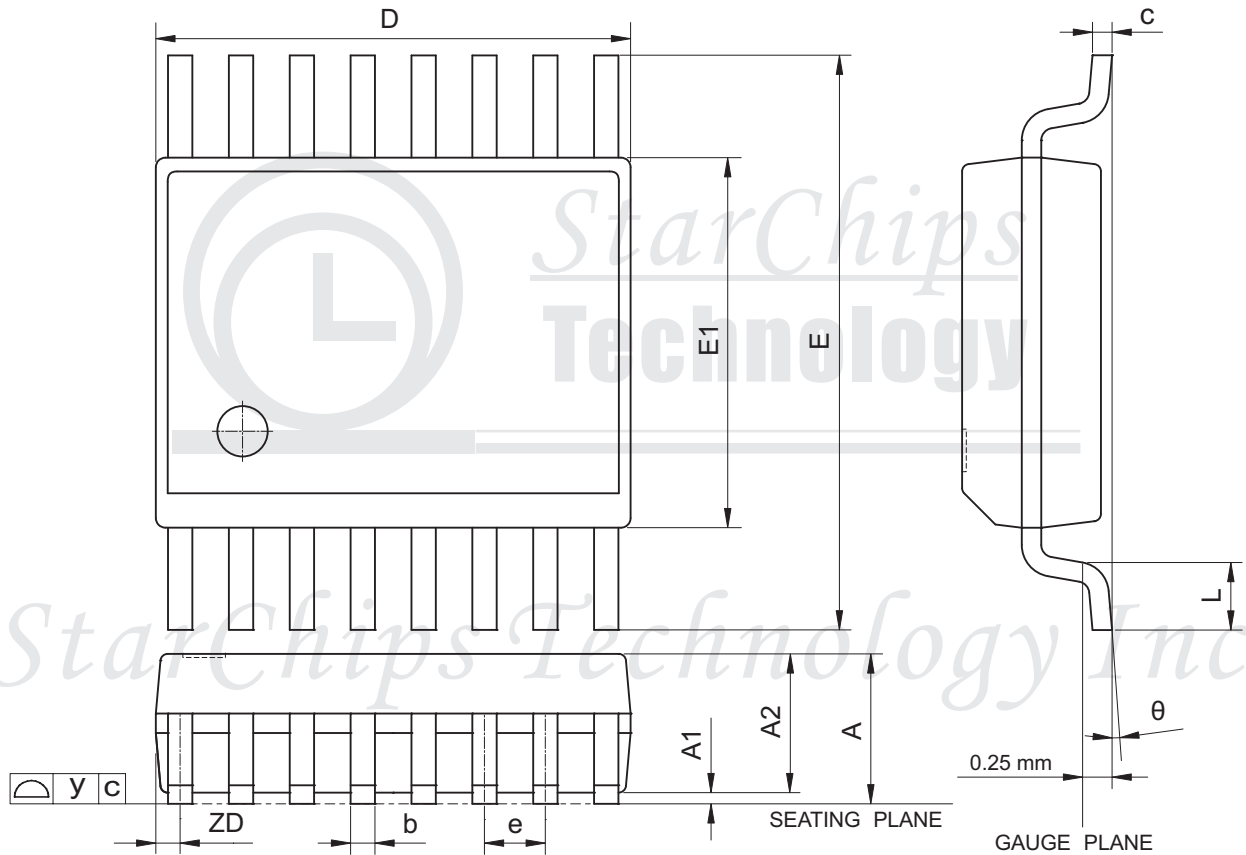
Locate the external resistor as close to the REXT pin as possible to avoid the noise influence.

Power and Ground

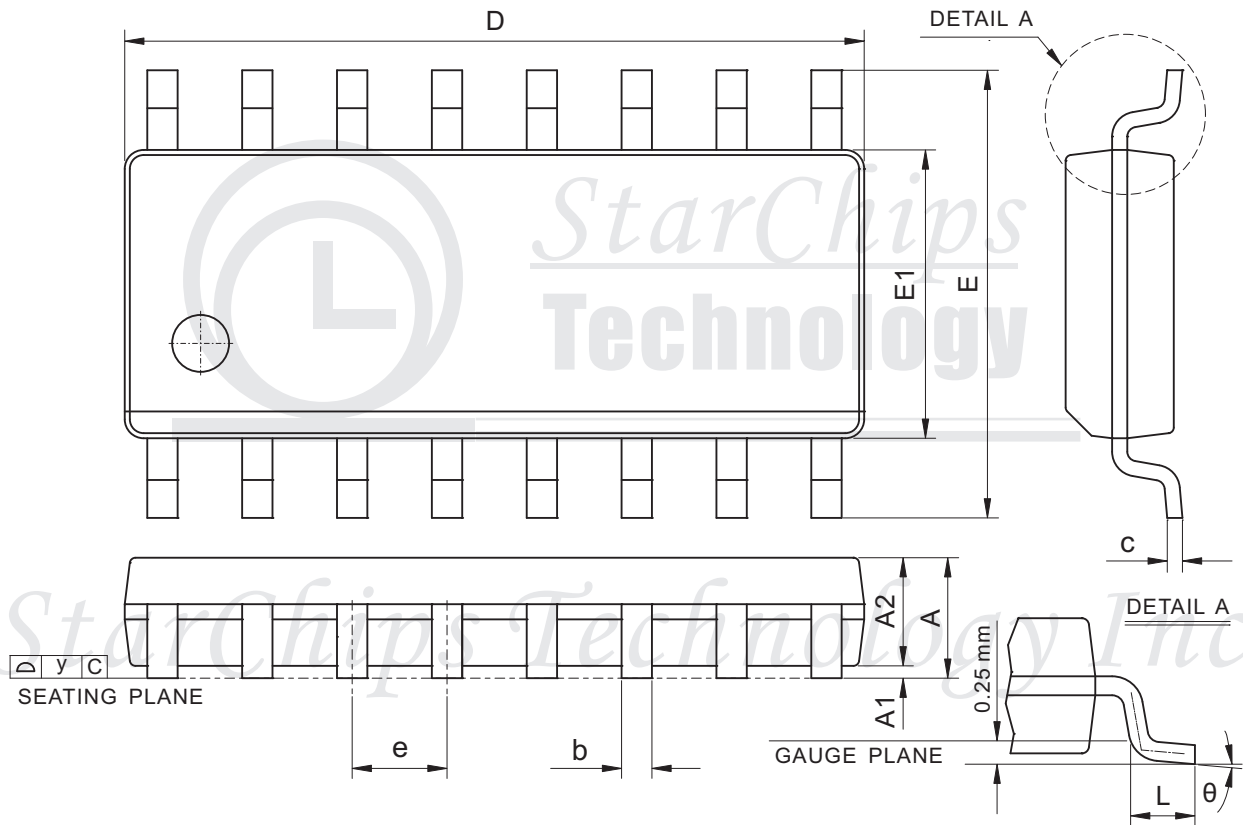
Maximizing the width and minimizing the length of VDD and GND trace improves efficiency and ground bouncing by effect of reducing both power and ground parasitic resistance and inductance. A small value of resistor, e.g., 10Ω (higher if I_{OUT} is larger) series in power input of the SCT2167 in conjunction with decoupling capacitor shunting the IC is recommended. Separating and feeding the LED power from another stable supply terminal V_{LED} , furthermore adding a capacitor C_{LED} greater than 10uF beside the LED are recommended. Please adapt C_{LED} according to total system current consumption.

EMI Reduction

To reduce the EMI radiation from system, an economical solution of RC low pass filter (LPF) is suggested to be used to lower the transient edge of clock input signal, as shown in the figure above. Using at least four layers PCB board with two interior power and ground planes is a good scheme to decrease the signal current path which is the source of radiation emission. As a result, EMI radiation can be decreased.

Package DimensionSSOP16([check up-to-date version](#))

Symbol	Dimension (mm)			Dimension (mil)		
	Min.	Nom.	Max.	Min.	Nom.	Max.
A	1.35	1.63	1.75	53.1	64.2	68.9
A1	0.10	0.15	0.25	3.9	5.9	9.8
A2	-	-	1.50	-	-	59.1
b	0.20	-	0.30	7.9	-	11.8
c	0.18	-	0.25	7.1	-	9.8
D	4.80	4.90	5.00	189.0	192.9	196.9
E	5.79	5.99	6.20	228.0	235.8	244.1
E1	3.81	3.91	3.99	150.0	153.9	157.1
e	0.64 BSC			25.0 BSC		
L	0.41	0.64	1.27	16.1	25.0	50.0
y	-	-	0.10	-	-	3.9
ZD	0.23 REF			9.0 REF		
theta	0°	-	8°	0°	-	8°

SOP16([check up-to-date version](#))

Symbol	Dimension (mm)			Dimension (mil)		
	Min.	Nom.	Max.	Min.	Nom.	Max.
A	1.35	-	1.75	53.1	-	68.9
A1	0.10	-	0.25	3.9	-	9.8
A2	1.10	-	1.65	43.3	-	65.0
b	0.33	-	0.51	13.0	-	20.1
c	0.19	-	0.25	7.5	-	9.8
D	9.80	-	10.00	385.8	-	393.7
E	5.80	-	6.20	228.3	-	244.1
E1	3.80	-	4.00	149.6	-	157.5
e	1.27 BSC			50.0 BSC		
L	0.40	-	1.27	15.7	-	50.0
θ	0°	-	8°	0°	-	8°
y	-	-	0.10	-	-	3.9

Revision History([check up-to-date version](#))

Data Sheet Version	Remark
V01_02	CSWG package removed & description added

Information provided by StarChips Technology is believed to be accurate and reliable. Application circuits shown, if any, are typical examples illustrating the operation of the devices. StarChips can not assume responsibility and any problem raising out of the use of the circuits. StarChips reserves the right to change product specification without prior notice.