Specifications



variable speed drive ATV12 -0.75kW - 1hp - 100..120V - 1ph with heat sink

ATV12H075F1

Main

Main	
Range of product	Altivar 12
Product or component type	Variable speed drive
Product specific application	Simple machine
Mounting mode	Cabinet mount
Communication port protocol	Modbus
Supply frequency	50/60 Hz +/- 5 %
[Us] rated supply voltage	100120 V - 1510 %
Nominal output current	4.2 A
Motor power hp	1 hp
Motor power kW	0.75 kW
	1 hp
EMC filter	Without EMC filter
IP degree of protection	IP20

Complementary

Discrete input number	4
Discrete output number	2
Analogue input number	1
Analogue output number	1
Relay output number	1
Physical interface	2-wire RS 485
Connector type	1 RJ45
Continuous output current	4.2 A at 4 kHz
Method of access	Server Modbus serial
Speed drive output frequency	0.5400 Hz
Speed range	120
Sampling duration	20 ms, tolerance +/- 1 ms for logic input 10 ms for analogue input
Linearity error	+/- 0.3 % of maximum value for analogue input
Frequency resolution	Analog input: converter A/D, 10 bits



	Display unit: 0.1 Hz	
Time constant	20 ms +/- 1 ms for reference change	
Transmission rate	9.6 kbit/s 19.2 kbit/s 38.4 kbit/s	
Transmission frame	RTU	
Number of addresses	1247	
Data format	8 bits, configurable odd, even or no parity	
Communication service	Read holding registers (03) 29 words Write single register (06) 29 words Write multiple registers (16) 27 words Read/write multiple registers (23) 4/4 words Read device identification (43)	
Type of polarization	No impedance	
4 quadrant operation possible	False	
Asynchronous motor control profile	Voltage/frequency ratio (V/f) Quadratic voltage/frequency ratio Sensorless flux vector control	
Maximum output frequency	4 kHz	
Transient overtorque	150170 % of nominal motor torque depending on drive rating and type of motor	
Acceleration and deceleration ramps	Linear from 0 to 999.9 s S U	
Motor slip compensation	Preset in factory Adjustable	
Switching frequency	216 kHz adjustable 416 kHz with derating factor	
Nominal switching frequency	4 kHz	
Braking to standstill	By DC injection	
Brake chopper integrated	False	
Line current	18.9 A at 100 V (heavy duty)	
	15.7 A at 120 V (heavy duty)	
Maximum input current		
	15.7 A at 120 V (heavy duty)	
Maximum input current	15.7 A at 120 V (heavy duty) 15.7 A 240 V 1.9 kVA at 240 V (heavy duty)	
Maximum input current Maximum output voltage	15.7 A at 120 V (heavy duty) 15.7 A 240 V	
Maximum input current Maximum output voltage Apparent power	15.7 A at 120 V (heavy duty) 15.7 A 240 V 1.9 kVA at 240 V (heavy duty) 6.3 A during 60 s (heavy duty)	
Maximum input current Maximum output voltage Apparent power Maximum transient current	15.7 A at 120 V (heavy duty) 15.7 A 240 V 1.9 kVA at 240 V (heavy duty) 6.3 A during 60 s (heavy duty) 6.9 A during 2 s (heavy duty)	
Maximum input current Maximum output voltage Apparent power Maximum transient current Network frequency Relative symmetric network	15.7 A at 120 V (heavy duty) 15.7 A 240 V 1.9 kVA at 240 V (heavy duty) 6.3 A during 60 s (heavy duty) 6.9 A during 2 s (heavy duty) 5060 Hz	
Maximum input current Maximum output voltage Apparent power Maximum transient current Network frequency Relative symmetric network frequency tolerance	15.7 A at 120 V (heavy duty) 15.7 A 240 V 1.9 kVA at 240 V (heavy duty) 6.3 A during 60 s (heavy duty) 6.9 A during 2 s (heavy duty) 5060 Hz	
Maximum input current Maximum output voltage Apparent power Maximum transient current Network frequency Relative symmetric network frequency tolerance Prospective line lsc Base load current at high	15.7 A at 120 V (heavy duty) 15.7 A 240 V 1.9 kVA at 240 V (heavy duty) 6.3 A during 60 s (heavy duty) 6.9 A during 2 s (heavy duty) 5060 Hz 5 % 1 kA	
Maximum input current Maximum output voltage Apparent power Maximum transient current Network frequency Relative symmetric network frequency tolerance Prospective line lsc Base load current at high overload	15.7 A at 120 V (heavy duty) 15.7 A 240 V 1.9 kVA at 240 V (heavy duty) 6.3 A during 60 s (heavy duty) 6.3 A during 2 s (heavy duty) 5060 Hz 5 % 1 kA 4.2 A	
Maximum input current Maximum output voltage Apparent power Maximum transient current Network frequency Relative symmetric network frequency tolerance Prospective line Isc Base load current at high overload Power dissipation in W With safety function Safely	15.7 A at 120 V (heavy duty) 15.7 A 240 V 1.9 kVA at 240 V (heavy duty) 6.3 A during 60 s (heavy duty) 6.3 A during 2 s (heavy duty) 5.060 Hz 5 % 1 kA 4.2 A Forced cooling: 48.0 W	
Maximum input currentMaximum output voltageApparent powerMaximum transient currentMetwork frequencyRelative symmetric network frequency toleranceProspective line IscBase load current at high overloadPower dissipation in WWith safety function Safely Limited Speed (SLS)With safety function Safe brake	15.7 A at 120 V (heavy duty) 15.7 A 240 V 1.9 kVA at 240 V (heavy duty) 6.3 A during 60 s (heavy duty) 6.9 A during 2 s (heavy duty) 5060 Hz 5 % 1 kA 4.2 A Forced cooling: 48.0 W False	
Maximum input currentMaximum output voltageApparent powerMaximum transient currentNetwork frequencyRelative symmetric network frequency toleranceProspective line IscBase load current at high overloadPower dissipation in WWith safety function Safely Limited Speed (SLS)With safety function Safe brake management (SBC/SBT)With safety function Safe	15.7 A at 120 V (heavy duty) 15.7 A 240 V 1.9 kVA at 240 V (heavy duty) 6.3 A during 60 s (heavy duty) 6.3 A during 2 s (heavy duty) 5.060 Hz 5 % 1 kA 4.2 A Forced cooling: 48.0 W False	

With safety function Safe Speed Monitor (SSM)	False	
With safety function Safe Stop 1 (SS1)	False	
With sft fct Safe Stop 2 (SS2)	False	
With safety function Safe torque off (STO)	False	
With safety function Safely Limited Position (SLP)	False	
With safety function Safe Direction (SDI)	False	
Protection type	Line supply overvoltage Line supply undervoltage Overcurrent between output phases and earth Overheating protection Short-circuit between motor phases Against input phase loss in three-phase Thermal motor protection via the drive by continuous calculation of I ² t	
Tightening torque	1.2 N.m	
Insulation	Electrical between power and control	
Quantity per set	Set of 1	
Width	105 mm	
Height	142 mm	
Depth	156.2 mm	
Net weight	1.3 kg	
Environment		
Operating altitude	> 10002000 m with current derating 1 % per 100 m <= 1000 m without derating	
Operating position	Vertical +/- 10 degree	
Product certifications	NOM CSA C-Tick UL GOST RCM KC	
Marking	CE	
Standards	UL 508C UL 618000-5-1 EN/IEC 61800-5-1 EN/IEC 61800-3	
Assembly style	With heat sink	
Electromagnetic compatibility	Electrical fast transient/burst immunity test level 4 conforming to EN/IEC 61000-4-4 Electrostatic discharge immunity test level 3 conforming to EN/IEC 61000-4-2 Immunity to conducted disturbances level 3 conforming to EN/IEC 61000-4-6 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to EN/IEC 61000-4-3 Surge immunity test level 3 conforming to EN/IEC 61000-4-5 Voltage dips and interruptions immunity test conforming to EN/IEC 61000-4-11	
Environmental class (during operation)	Class 3C3 according to IEC 60721-3-3 Class 3S2 according to IEC 60721-3-3	
Maximum acceleration under shock impact (during operation)	150 m/s² at 11 ms	
Maximum acceleration under vibrational stress (during operation)	10 m/s² at 13200 Hz	
Maximum deflection under vibratory load (during operation)	1.5 mm at 213 Hz	

May 31, 2023

Volume of cooling air

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16 m3/h

Overvoltage category	Class III	
Regulation loop	Adjustable PID regulator	
Electromagnetic emission	Radiated emissions environment 1 category C2 conforming to EN/IEC 61800-3 216 kHz shielded motor cable Conducted emissions with additional EMC filter environment 1 category C1 conforming to EN/IEC 61800-3 412 kHz shielded motor cable <5 m Conducted emissions with additional EMC filter environment 1 category C2 conforming to EN/IEC 61800-3 412 kHz shielded motor cable <20 m Conducted emissions with additional EMC filter environment 2 category C3 conforming to EN/IEC 61800-3 412 kHz shielded motor cable <20 m	
Vibration resistance	1 gn (f = 13200 Hz) conforming to EN/IEC 60068-2-6 1.5 mm peak to peak (f = 313 Hz) - drive unmounted on symmetrical DIN rail - conforming to EN/IEC 60068-2-6	
Shock resistance	15 gn conforming to EN/IEC 60068-2-27 for 11 ms	
Relative humidity	595 % without condensation conforming to IEC 60068-2-3 595 % without dripping water conforming to IEC 60068-2-3	
Noise level	45 dB	
Pollution degree	2	
Ambient air transport temperature	-2570 °C	
Ambient air temperature for operation	-1050 °C without derating 5060 °C with current derating 2.2 % per °C	
Ambient air temperature for storage	-2570 °C	
Packing Units		
Unit Type of Package 1	PCE	
Number of Units in Package 1	1	
Package 1 Height	17.000 cm	
Package 1 Width	19.500 cm	
Package 1 Length	19.000 cm	
Package 1 Weight	1.587 kg	
Unit Type of Package 2	P06	
Number of Units in Package 2	30	
Package 2 Height	75.000 cm	
Package 2 Width	60.000 cm	
Package 2 Length	80.000 cm	
Package 2 Weight	59.600 kg	
Offer Sustainability		
Sustainable offer status	Green Premium product	
REACh Regulation	REACh Declaration	
EU RoHS Directive	Pro-active compliance (Product out of EU RoHS legal scope) EU RoHS Declaration	
Mercury free	Yes	
China RoHS Regulation	China RoHS declaration	

WEEE

Environmental Disclosure

Circularity Profile

The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins

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Product Environmental Profile

End of Life Information

WARNING: This product can expose you to chemicals including: Lead and lead compounds, which is known to the State of California to cause cancer and birth defects or other reproductive harm. For more information go to www.P65Warnings.ca.gov

Contractual warranty

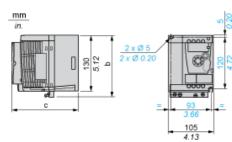
Warranty

18 months

Dimensions Drawings

Dimensions

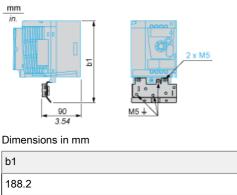
Drive without EMC Conformity Kit



Dimensions in mm

b	C	
142	156.2	
Dimensions in in.		
b	c	
5.59	6.15	

Drive with EMC Conformity Kit



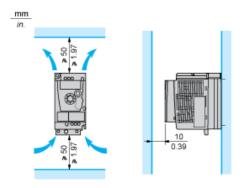
Dimensions in mm
b1
188.2
Dimensions in in.
b1
7.41

Mounting and Clearance

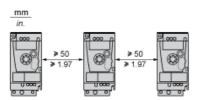
ATV12H075F1

Mounting Recommendations

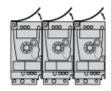
Clearance for Vertical Mounting



Mounting Type A

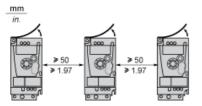


Mounting Type B



Remove the protective cover from the top of the drive.

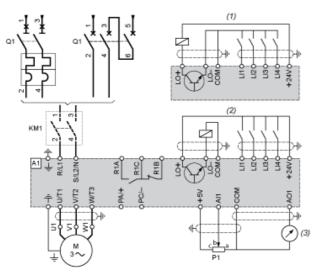
Mounting Type C



Remove the protective cover from the top of the drive.

Connections and Schema

Single-Phase Power Supply Wiring Diagram



- Drive Contactor (only if a control circuit is needed) 2.2 kΩ reference potentiometer. This can be replaced by a 10 kΩ potentiometer (maximum). Circuit breaker Negative logic (Sink) Positive logic (Source) (factory set configuration) 0...10 V or 0...20 mA
- A1 KM1 P1 Q1 (1) (2) (3)

Connections and Schema

Recommended Schemes

2-Wire Control for Logic I/O with Internal Power Supply



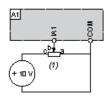
LI• : Reverse A1 : Drive

3-Wire Control for Logic I/O with Internal Power Supply



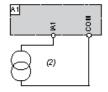
LI• : Reverse A1 : Drive

Analog Input Configured for Voltage with Internal Power Supply



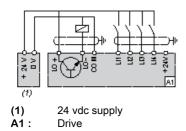
(1) A1 : 2.2 k $\Omega...10$ k Ω reference potentiometer Drive

Analog Input Configured for Current with Internal Power Supply

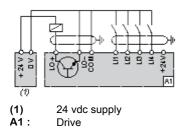


(2) A1 : 0-20 mA 4-20 mA supply Drive

Connected as Positive Logic (Source) with External 24 vdc Supply

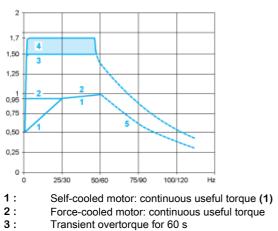


Connected as Negative Logic (Sink) with External 24 vdc supply



Performance Curves

Torque Curves



- 4: Transient overtorque for 2 s
- 5: Torque in overspeed at constant power (2)
- (1) (2) For power ratings ≤ 250 W, derating is 20% instead of 50% at very low frequencies.
 - The nominal motor frequency and the maximum output frequency can be adjusted from 0.5 to 400 Hz. The mechanical overspeed capability of the

Recommended replacement(s)