



# Incremental Encoders

<b>Economy, optical</b>	<b>3700 / 3720 (Shaft / Hollow shaft)</b>	<b>Push-Pull / RS422</b>
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Mechanical characteristics		
<b>Speed</b>		max. 6 000 min <sup>-1</sup>
<b>Rotor moment of inertia</b>	shaft version	approx. 0.4 x 10 <sup>-6</sup> kgm <sup>2</sup>
	hollow shaft version	1.4 x 10 <sup>-6</sup> kgm <sup>2</sup>
<b>Starting torque</b>	shaft version	< 0.007 Nm
	hollow shaft version	< 0.01 Nm
<b>Shaft load capacity</b>	radial	20 N
	axial	10 N
<b>Weight</b>		approx. 0.1 kg
<b>Protection to EN 60529</b>	bearings, shaft	IP65
	cable outlet	IP67
<b>EX approval for hazardous areas</b>		optional Zone 2 and 22
<b>Working temperature range</b>		-20°C ... +70°C <sup>1)</sup>
<b>Materials</b>	shaft / hollow shaft	stainless steel
	housing, flange	PPA, 40% CF (carbon fibre)
	cable	PVC
<b>Shock resistance</b> acc. to EN 60068-2-27		1000 m/s <sup>2</sup> , 6 ms
<b>Vibration resistance</b> acc. to EN 60068-2-6		100 m/s <sup>2</sup> , 10 ... 2000 Hz

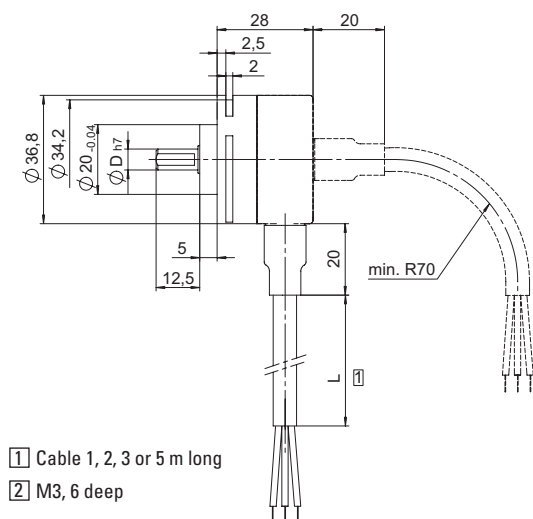
Electrical characteristics			
<b>Output circuit</b>	<b>RS422</b> (TTL compatible)	<b>Push-Pull</b> (7272) <sup>4)</sup>	<b>Push-Pull</b> (7272) <sup>4)</sup>
<b>Supply voltage</b>	5 V (±5%)	5 ... 30 V DC	10 ... 30 V DC
<b>Power consumption with inverted signal</b> (no load)	typ. 40 mA / max. 90 mA	typ. 50 mA / max. 100 mA	typ. 50 mA / max. 100 mA
<b>Permissible load / channel</b>	max. ±20 mA	max. ±20 mA	max. ±20 mA
<b>Pulse frequency</b>	max. 250 kHz	max. 250 kHz	max. 250 kHz
<b>Signal level</b>	high	min. 2.5 V	min. U <sub>B</sub> - 2.0 V
	low	max. 0.5 V	max. 0.5 V
<b>Rising edge time t<sub>r</sub></b>	max. 200 ns	max. 1 µs	max. 1 µs
<b>Falling edge time t<sub>f</sub></b>	max. 200 ns	max. 1 µs	max. 1 µs
<b>Short circuit proof outputs</b> <sup>2)</sup>	yes <sup>3)</sup>	yes	yes
<b>Reverse connection of the supply voltage</b>	no	no	yes
<b>UL-certified</b>	File 224618		
<b>CE compliant</b> acc. to	EN 61000-6-2, EN 61000-6-4 and EN 61000-6-3		
<b>RoHS compliant</b> acc. to	EU guideline 2002/95/EG		

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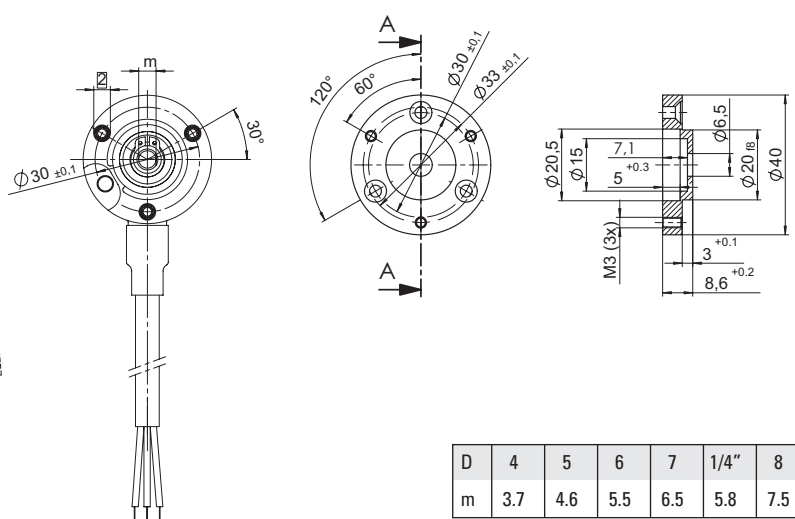
### Terminal assignment

Signal	0V	+UB	A	$\bar{A}$	B	$\bar{B}$	0	$\bar{0}$
Cable colour	WH	BN	GN	YE	GY	PK	BU	RD

### Dimensions shaft version



### Adapting flange Type A



### Mounting advice

The flanges and shafts of the encoder and drive should not both be rigidly coupled together at the same time! We recommend the use of suitable couplings (see Accessories section).

1) For versions with push-pull output and supply voltage >15 V DC: max. 55°C  
 2) If supply voltage correctly applied.

3) Only one channel allowed to be shorted-out:  
 If U<sub>B</sub> = 5 V short circuit to channel, 0 V, or +U<sub>B</sub> is permitted.  
 If U<sub>B</sub> = 5 ... 30 V short circuit to channel or 0 V is permitted.  
 4) Max. recommended cable length 30 m

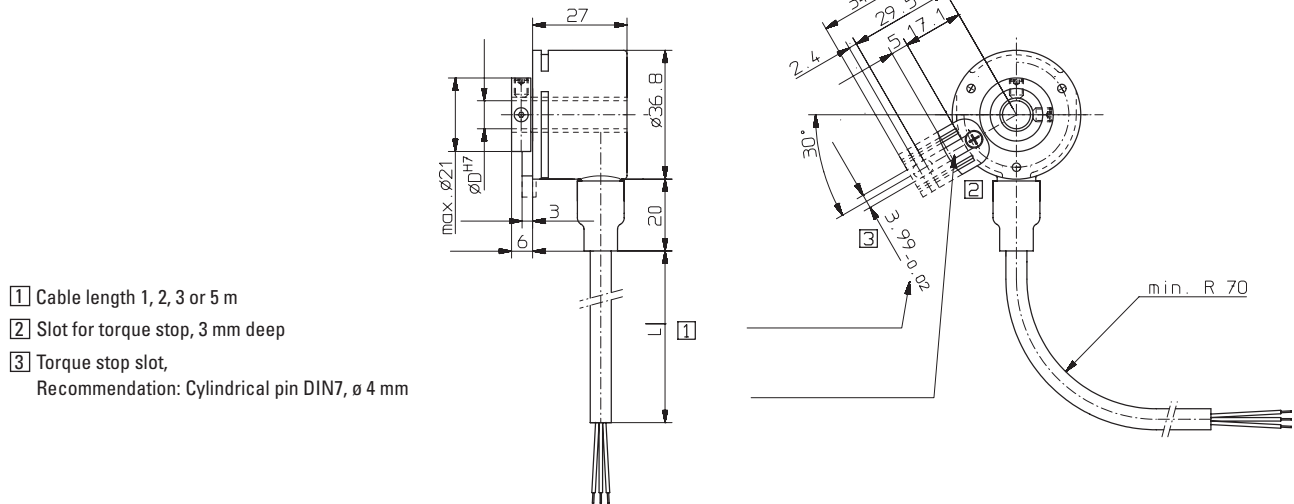
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## Dimensions hollow shaft version

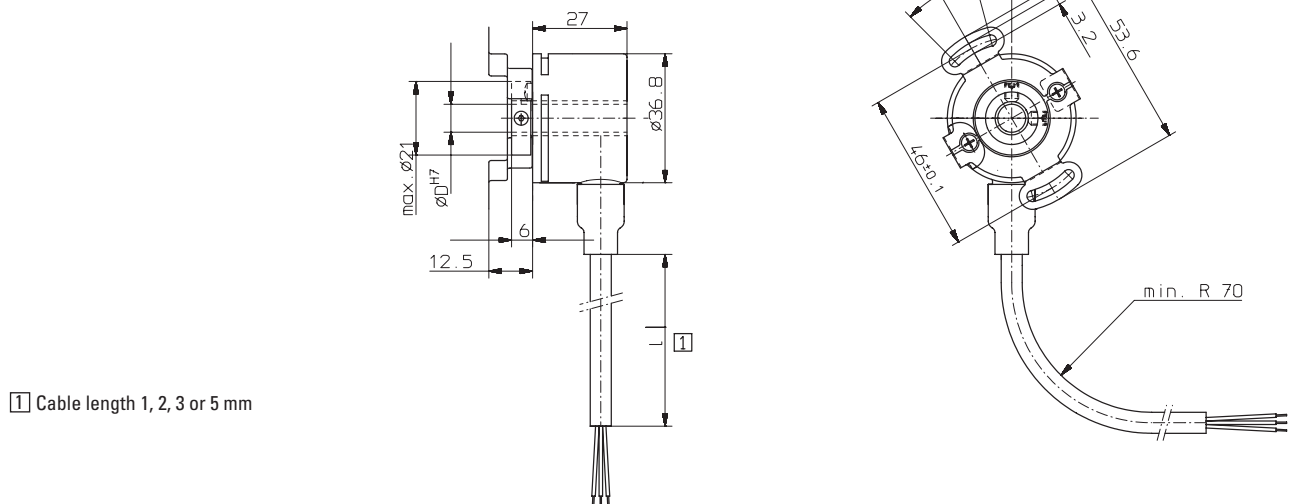
### Flange with torque stop short

Long torque stop version is shown dashed



- 1 Cable length 1, 2, 3 or 5 m
- 2 Slot for torque stop, 3 mm deep
- 3 Torque stop slot,  
Recommendation: Cylindrical pin DIN7,  $\phi$  4 mm

### Flange with stator coupling, double-winged



- 1 Cable length 1, 2, 3 or 5 mm