

# NEO-D9S-00B

## Correction data receiver Professional grade

Data sheet



#### **Abstract**

Technical data sheet describing the u-blox D9 correction data receiver. The module provides global and easy access to satellite L-band GNSS corrections.





### **Document information**

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Product status	Corresponding content status	
Functional Sample	Draft	For functional testing. Revised and supplementary data will be published later.
In development / prototype	Objective specification	Target values. Revised and supplementary data will be published later.
Engineering sample	Advance information	Data based on early testing. Revised and supplementary data will be published later.
Initial production	Early production information	Data from product verification. Revised and supplementary data may be published later.
Mass production / End of life	Production information	Document contains the final product specification.

#### This document applies to the following products:

Product name	Type number	FW version	IN/PCN reference	Product status
NEO-D9S	NEO-D9S-00B-00	PMP 1.04	UBX-22001724 UBX-22039049	Mass production

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## 1 Functional description

### 1.1 Overview

NEO-D9S-00B is a satellite data receiver for L-band correction broadcast, which can be configured for use with a variety of correction services. It decodes the satellite transmission and outputs a correction stream, enabling a high precision GNSS receiver to reach accuracies down to centimeter level.

#### 1.2 Performance

Parameter		Specification		
Receiver type		NEO-D9S correction data receiver		
L-band satellite		Specification		
Time to first frame <sup>1</sup>		< 10 s at 2400 bps		
Sensitivity acquisition <sup>2</sup>		-133 dBm for BER <10e-5 at 2400 bit/s		
Specification compliance		L-band SESTB28A		
Boot time		<1 s		
Center frequency configuration steps		1 Hz		
Center frequency search window		0 to 65 kHz		
User data rates		600, 1200, 2400, 4800 bps		
Service identifier		Configurable		
De-scrambler		Configurable		
De-scrambling initialization vector		Configurable		
Pre-scrambler		Enable/disable		
Number of concurrent reception channels		1		
UniqueWord		Configurable		
Frequency range		1525 MHz to 1559 MHz		
Communication interface		UART/USB/I2C/SPI		
Communication speed		Up to 921600 baud UART, USB 2.0		
Software backup mode		Available		
Vehicle dynamics	Dynamics	+/- 2g acceleration for all data rates (600 bit/s, 1200 bit/s, 2400 bit/s, 4800 bit/s)		
-	Velocity	Up to and including 300 km/h		

Table 1: NEO-D9S-00B performance

## 1.3 Supported GNSS augmentation systems

#### 1.3.1 Satellite L-band

The satellite L-band communication system allows GNSS correction service providers to broadcast a variety of services on specific channels, satellites and beams. Consult your service provider on the region their service covers and the specific frequency used. The NEO-D9S-00B must be configured

<sup>1</sup> With respect to an L-band signal using a 20-25 dB external LNA

 $<sup>^2</sup>$  Success rate of acquiring an L-band signal > 95% using a 20-25 dB external LNA



according to the specific service as initial identification and decoding of the service provider stream is required.

### 1.4 Supported protocols

The NEO-D9S-00B supports the following protocols:

UBX Input/output, binary, u-blo	
	proprietary

Table 2: Supported protocols

For specification of the protocols, see the Interface description [2].



# 2 System description

## 2.1 Block diagram

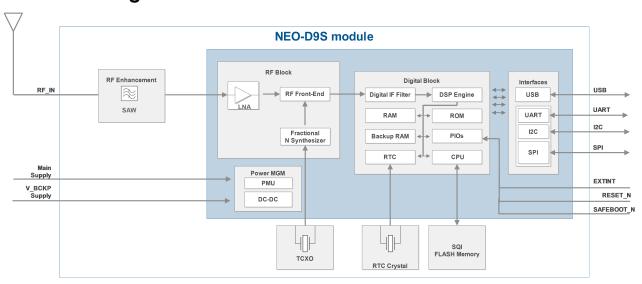


Figure 1: NEO-D9S-00B block diagram

An active antenna is mandatory with the NEO-D9S-00B.



### 3 Pin definition

### 3.1 Pin assignment

The pin assignment of the NEO-D9S-00B module is shown in Figure 2. The defined configuration of the PIOs is listed in Table 3.

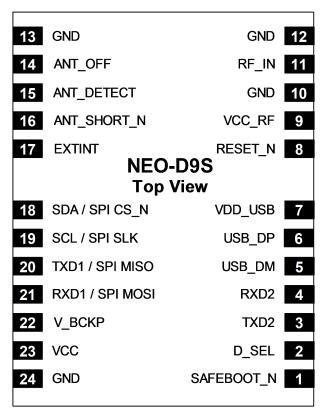


Figure 2: NEO-D9S-00B pin assignment

Pin no.	Name	I/O	Description
1	SAFEBOOT_N	1	SAFEBOOT_N (used for FW updates and reconfiguration, leave open)
2	D_SEL	I	UART 1 / SPI select. (open or high = UART 1)
3	TXD2	0	UART 2 TXD
4	RXD2	I	UART 2 RXD
5	USB_DM	I/O	USB data (DM)
6	USB_DP	I/O	USB data (DP)
7	V_USB	I	USB supply
8	RESET_N	I	RESET (active low)
9	VCC_RF	0	External LNA power
10	GND	I	Ground
11	RF_IN	I	Active antenna L-band signal input
12	GND	I	Ground
13	GND	I	Ground
14	ANT_OFF	0	External LNA disable - default active high



Pin no.	Name	1/0	Description
15	ANT_DETECT	I	Active antenna detect - default active high
16	ANT_SHORT_N	0	Active antenna short detect - default active low
17	EXTINT	I	External interrupt pin
18	SDA/SPICS_N	I/O	I2C data if D_SEL = VCC (or open); SPI chip select if D_SEL = GND
19	SCL/SPISLK	I/O	I2C clock if D_SEL = VCC (or open); SPI clock if D_SEL = GND
20	TXD/SPI MISO	0	UART1 output if D_SEL = VCC (or open); SPI MISO if D_SEL = GND
21	RXD/SPI MOSI	I	UART1 input if D_SEL = VCC (or open); SPI MOSI if D_SEL = GND
22	V_BCKP	I	Connect to VCC or leave it open
23	VCC	I	Supply voltage
24	GND	I	Ground

Table 3: NEO-D9S-00B pin assignment



For detailed information on the pin functions and characteristics see the integration manual [1].



## 4 Electrical specification

The limiting values given are in accordance with the Absolute Maximum Rating System (IEC 134).



**CAUTION** Operating the device above one or more of the limiting values may cause permanent damage to the device. The values provided in this chapter are stress ratings. Extended exposure to the values outside the limits may effect the device reliability.



Where application information is given, it is advisory only and does not form part of the specification.

### 4.1 Absolute maximum ratings

Parameter	Symbol	Condition	Min	Max	Units
Power supply voltage	VCC		-0.5	3.6	V
Voltage ramp on VCC <sup>3</sup>			20	8000	μs/V
Input pin voltage	Vin		-0.5	VCC + 0.5	V
VCC_RF output current	ICC_RF			100	mA
Supply voltage USB	V_USB		-0.5	3.6	V
USB signals	USB_DM, USB_DP		-0.5	V_USB + 0.	5 V
Input power at RF_IN	Prfin	source impedance = $50 \Omega$ , continuous wave		10	dBm
Storage temperature	Tstg		-40	+85	°C
Storage temperature					

Table 4: Absolute maximum ratings



**CAUTION** Risk of equipment damage. This product is not protected against overvoltage or reversed voltages. Use appropriate protection diodes to avoid voltage spikes exceeding the specified boundaries damaging the equipment.

### 4.2 Operating conditions



The values for the following operating conditions have been specified at 25°C ambient temperature. Extreme operating temperatures can significantly impact the specified values. If an application operates near the min or max temperature limits, ensure the specified values are not exceeded.

Parameter	Symbol	Min	Typical	Max	Units	Condition
Power supply voltage	VCC	2.7	3.0	3.6	V	
SW backup current	I_SWBCKP		0.36		mA	
Input pin voltage range	Vin	0		VCC	V	
Digital IO pin low level input voltage	Vil			0.4	V	
Digital IO pin high level input voltage	Vih	0.8 * VCC			V	
Digital IO pin low level output voltage	Vol			0.4	V	Iol = 2 mA
Digital IO pin high level output voltage	Voh	VCC - 0.4			V	loh = 2 mA
DC current through any digital I/O pin (except supplies)	lpin			5	mA	
VCC_RF voltage	VCC_RF		VCC - 0.1		V	
VCC_RF output current	ICC_RF			50	mA	

 $<sup>^{\</sup>rm 3}~$  Exceeding the ramp speed may permanently damage the device



Parameter	Symbol	Min	Typical	Max	Units	Condition
Receiver chain noise figure <sup>4</sup>	NFtot		11		dB	,
Recommended LNA gain into module	e LNA_gain		20		dB	
Operating temperature	Topr	-40	+25	+85	°C	

**Table 5: Operating conditions** 



Operation beyond the specified operating conditions can affect the device reliability.

### 4.3 Indicative power requirements

Table 6 provides examples of typical current requirements when using a cold start command. The given values are total system supply current for a possible application including RF and baseband sections.



The actual power requirements vary depending on the FW version used, external circuitry, number of satellites tracked, signal strength, type and time of start, duration, and conditions of test.

Symbol	Parameter	Conditions	L - band Unit SESTB28A
I <sub>PEAK</sub>	Peak current	Acquisition & tracking	130 mA
I <sub>AVERAGE</sub>	Average current	Acquisition & tracking	35 mA

Table 6: Currents to calculate the indicative power requirements

All values in Table 6 are measured at 25 °C ambient temperature.

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<sup>&</sup>lt;sup>4</sup> Only valid for the L-band band



### 5 Communications interfaces

There are several communications interfaces including UART, SPI, I2C and USB.

#### **5.1 UART**

UART1 is the main UART interface for UBX protocol host control and message output.

Symbol	Parameter	Min	Max	Unit
R <sub>u</sub>	Baud rate	9600	921600	bit/s
$\Delta_{Tx}$	Tx baud rate accuracy	-1%	+1%	-
$\Delta_{Rx}$	Rx baud rate tolerance	-2.5%	+2.5%	-

Table 7: NEO-D9S-00B UART specifications

#### 5.2 SPI

The NEO-D9S-00B has an SPI slave interface that can be selected by setting D\_SEL = 0. The SPI slave interface is shared with UART1. The SPI pins available are: SPI\_MISO (TXD), SPI\_MOSI (RXD), SPI\_CS\_N, SPI\_CLK. The SPI interface is designed to allow communication to a host CPU. The interface can be operated in slave mode only. Note that SPI is not available in the default configuration because its pins are shared with the UART1 and I2C interfaces. The maximum transfer rate using SPI is 125 kB/s and the maximum SPI clock frequency is 5.5 MHz.

This section provides SPI timing values for the NEO-D9S-00B slave operation. The following tables present timing values under different capacitive loading conditions. Default SPI configuration is CPOL = 0 and CPHA = 0.

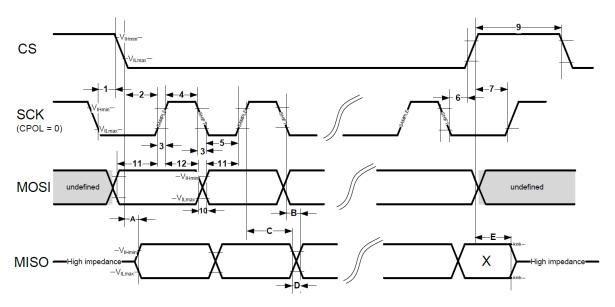


Figure 3: NEO-D9S-00B SPI specification mode 1: CPHA=0 SCK = 5.33 MHz



Timings 1 - 12 are not specified here.

Timing value at 2 pF load	Min (ns)	Max (ns)	
"A" - MISO data valid time (CS)	14	38	
"B" - MISO data valid time (SCK) weak driver mode	21	38	
"C" - MISO data hold time	114	130	



Timing value at 2 pF load	Min (ns)	Max (ns)
"D" - MISO rise/fall time, weak driver mode	1	4
"E" - MISO data disable lag time	20	32

#### Table 8: NEO-D9S-00B SPI timings at 2pF load

Timing value at 20 pF load	Min (ns)	Max (ns)	
"A" - MISO data valid time (CS)	19	52	
"B" - MISO data valid time (SCK) weak driver mode	25	51	
"C" - MISO data hold time	117	137	
"D" - MISO rise/fall time, weak driver mode	6	16	
"E" - MISO data disable lag time	20	32	

Table 9: NEO-D9S-00B SPI timings at 20pF load

Timing value at 60 pF load	Min (ns)	Max (ns)	
"A" - MISO data valid time (CS)	29	79	
"B" - MISO data valid time (SCK) weak driver mode	35	78	
"C" - MISO data hold time	122	152	
"D" - MISO rise/fall time, weak driver mode	15	41	
"E" - MISO data disable lag time	20	32	

Table 10: NEO-D9S-00B SPI timings at 60pF load

#### 5.3 I2C

An I2C compliant interface is available for communication with an external host CPU. The interface can be operated in slave mode only. It is fully compatible with Fast-mode of the I2C industry standard. Since the maximum SCL clock frequency is 400 kHz, the maximum bit rate is 400 kbit/s. The interface stretches the clock when slowed down while serving interrupts, therefore the real bit rates may be slightly lower.



The I2C interface is only available with the UART default mode. If the SPI interface is selected by using D\_SEL = 0, the I2C interface is not available.



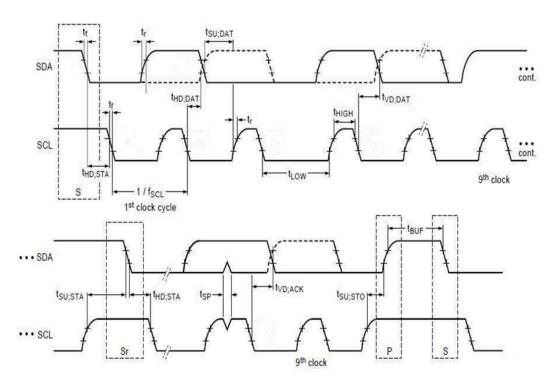


Figure 4: NEO-D9S-00B I2C slave specification

Symbol	Parameter	Min (Standard / Fast-mode)	Max	Unit
f <sub>SCL</sub>	SCL clock frequency	0	400	kHz
t <sub>HD;STA</sub>	Hold time (repeated) START condition	4.0/1	-	μs
t <sub>LOW</sub>	Low period of the SCL clock	5/2	-	μs
t <sub>HIGH</sub>	High period of the SCL clock	4.0/1	-	μs
t <sub>SU;STA</sub>	Setup time for a repeated START condition	5/1	-	μs
t <sub>HD;DAT</sub>	Data hold time	0/0	-	μs
t <sub>SU;DAT</sub>	Data setup time	250/100		ns
t <sub>r</sub>	Rise time of both SDA and SCL signals	-	1000/300 (for C 400pF)	ns
t <sub>f</sub>	Fall time of both SDA and SCL signals	-	300/300 (for C 400pF)	ns
t <sub>su;sto</sub>	Setup time for STOP condition	4.0/1	-	μs
t <sub>BUF</sub>	Bus-free time between a STOP and START condition	5/2	-	μs
t <sub>VD;DAT</sub>	Data-valid time	-	4/1	μs
t <sub>VD;ACK</sub>	Data-valid acknowledge time	-	4/1	μs
V <sub>nL</sub>	Noise margin at the low level	0.1 VCC	-	V
V <sub>nH</sub>	Noise margin at the high level	0.2 VCC	-	V

Table 11: NEO-D9S-00B I2C slave timings and specifications

### **5.4 USB**

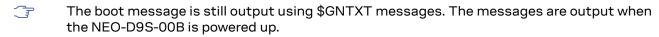
The USB 2.0 FS (Full Speed, 12 Mbit/s) interface can be used for host communication. Due to the hardware implementation, it may not be possible to certify the USB interface. The V\_USB pin supplies the USB interface.



## 5.5 Default interface settings

Interface	Settings	
UART 9600 baud, 8 bits, no parity bit, 1 stop bit.		
	Output protocol: UBX.	
	Input protocols without need of additional configuration: UBX.	
USB	Output messages activated as in UART. Input protocols available as in UART.	
I2C	Output messages activated as in UART. Input protocols available as in UART.	
SPI Output messages activated as in UART. Input protocols available as in UART.		

#### Table 12: Default interface settings



Refer to the applicable interface description [2] for information about further settings.



# 6 Mechanical specification

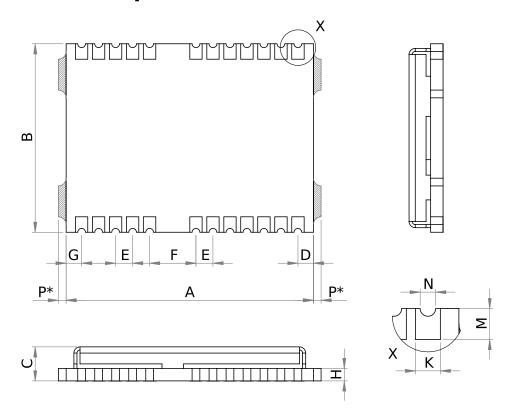


Figure 5: NEO-D9S-00B mechanical drawing

Symbol	Min (mm)	Typical (mm)	Max (mm)	
А	15.9	16.0	16.1	
В	12.1	12.2	12.3	
С	2.2	2.4	2.6	
D	0.9	1.0	1.1	
E	1.0	1.1	1.2	
F	2.9	3.0	3.1	
G	0.9	1.0	1.1	
Н	-	0.82	-	
K	0.7	0.8	0.9	
M	0.8	0.9	1.0	
N	0.4	0.5	0.6	
P*	0.0	-	0.5	The de-paneling residual tabs may be on either side (not both).
Weight		1.6 g		

Table 13: NEO-D9S-00B mechanical dimensions



- The mechanical picture of the de-paneling residual tabs (P\*) is an approximate representation, shape and position may vary.
- Component keep-out area must consider that the de-paneling residual tabs can be on either side (not both).



## 7 Reliability tests and approvals

NEO-D9S-00B modules are based on AEC-Q100 qualified GNSS chips.

Tests for product family qualifications comply with ISO 16750 "Road vehicles – environmental conditions and testing for electrical and electronic equipment", and appropriate standards.

### 7.1 Approvals

NEO-D9S-00B complies with the essential requirements and other relevant provisions of the Radio Equipment Directive (RED) 2014/53/EU.

NEO-D9S-00B complies with the Directive 2011/65/EU (EU RoHS 2) and its amendment Directive (EU) 2015/863 (EU RoHS 3).

The Declaration of Conformity (DoC) is available on the u-blox website.



## 8 Labeling and ordering information

This section provides information about product labeling and ordering. For information about moisture sensitivity level (MSL), product handling and soldering see the Integration manual [1].

#### 8.1 Product labeling

The labeling of the NEO-D9S-00B modules provides product information and revision information. For more information contact u-blox sales.

### 8.2 Explanation of product codes

Three product code formats are used in the NEO-D9S-00B labels. The **Product name** used in documentation such as this data sheet identifies all u-blox products, independent of packaging and quality grade. The **Ordering code** includes options and quality, while the **Type number** includes the hardware and firmware versions.

Table 14 below details these three formats.

Format	Structure	Product code
Product name	PPP-TGV	NEO-D9S
Ordering code	PPP-TGV-NNQ	NEO-D9S-00B
Type number	PPP-TGV-NNQ-XX	NEO-D9S-00B-00

Table 14: Product code formats

The parts of the product code are explained in Table 15.

Code	Meaning	Example
PPP	Product family	NEO
TG	Platform	D9 = u-blox D9
V	Variant	S = L-band corrections
NNQ	Option / Quality grade	NN: Option [0099]
		Q: Grade, A = Automotive, B = Professional
XX	Product detail	Describes hardware and firmware versions

Table 15: Part identification code

### 8.3 Ordering codes

Ordering code	Product	Remark
NEO-D9S-00B	NEO-D9S correction data receiver	u-blox D9 correction data receiver for L-band broadcast

Table 16: Product ordering codes



Product changes affecting form, fit or function are documented by u-blox. For a list of Product Change Notifications (PCNs) see our website at: https://www.u-blox.com/en/product-resources.



### **Related documents**

- [1] NEO-D9S Integration manual UBX-19026111
- [2] PMP 1.04 Interface description UBX-21040023



For regular updates to u-blox documentation and to receive product change notifications please register on our homepage https://www.u-blox.com.



# **Revision history**

Revision	Date	Name	Status / comments
R01	26-Mar-2018	jhak	Objective Specification
R02	26-Apr-2019	jhak	Objective Specification
R03	28-June-2019	ghun	Objective Specification - V_BCKP removed
R04	26-Nov-2019	ghun/jhak	Advance Information - V_BCKP pin connect to VCC. I2C, SPI, antenna supervisor, EXTINT, software backup mode added.
R05	05-Feb-2020	ghun/jhak	Early production information - USB added to Absolute maximum ratings table. Vil and Vih updated in Operating conditions table.
R06	27-Oct-2020	dama	USB Interface section update. UART interface section update
R07	24-Jan-2022	dama	Production information - Voltage ramp on VCC value added in Absolute maximum ratings table. V_BCKP general update.
R08	16-Dec-2022	dbhu	Overall text improvement Updated the section Mechanical specification



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